



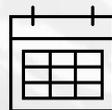
BIODRONES
PRIN 2022



SAPIENZA
UNIVERSITÀ DI ROMA

PROJECT CLOSING WORKSHOP

Biomimetic and Innovative Optimized hydrodynamic concepts of high-efficiency underwater gliding DRONES for ocean research



Wednesday February 25, 2026 – h. 09:00 – 13:00

Università Roma Tre

Dept. of Civil, Computer Science and Aeronautical Technology Engineering

[Via della Vasca Navale 79, Room N13](#)

09:00

Prof. Umberto Iemma (Roma Tre), Welcome address

09:10

Dr. Matteo Diez (CNR-INM), BIODRONES: A highly multidisciplinary project on biomimetic hydrodynamic concepts of high-efficiency underwater gliding drones for ocean research

09:30

Dr. Andrea Serani (CNR-INM), How to survive the curse of dimensionality with examples for underwater gliding drones

10:15

Mr. Andrea Brillì (Sapienza), A clustering technique for multi-fidelity surrogate-based multi-objective optimization

11:00

Break

11:30

Dr. Lorenzo Burghignoli (Roma Tre), Dynamic neural networks for the hydrodynamic optimization of a closed-wing underwater glider

12:15

Dr. Simona Aracri (CNR-INM), Unconventional marine robotics for extreme environments

<https://sites.google.com/inm.cnr.it/biodrones>

<https://www.linkedin.com/company/biodrones>



Finanziato
dall'Unione europea
NextGenerationEU



Ministero
dell'Università
e della Ricerca



Italiadomani
PIANO NAZIONALE
DI RIPRESA E RESILIENZA



Consiglio Nazionale
delle Ricerche

Biomimetic and Innovative Optimized hydrodynamic concepts of high-efficiency underwater gliding DRONES for ocean research

THE PROJECT

- ❑ The BIODRONES project aims to optimize hydrodynamic designs for compact autonomous underwater gliders (AUGs) tailored for ocean surveying. These designs seek maximum efficiency, range, and endurance within set constraints. The project's objectives include providing guidance for next-gen AUGs, enabling cost-effective ocean data collection, and promoting technology transfer to small and medium underwater robotics enterprises.
- ❑ AUGs offer cost-effective, long-range data collection capabilities, measuring various ocean parameters. Buoyancy control methods involve seawater flooding/evacuation or adjusting oil levels in an external bladder. Efficient hydrodynamic designs are crucial for equilibrium between lift, drag, and buoyancy force, ensuring extended missions.
- ❑ The project explores biomimetic and innovative glider concepts inspired by nature (rays, sea turtles) and other industries (aircraft design). To ensure a fair comparison, all concepts undergo high-fidelity hydrodynamic optimization using simulation-driven methodologies, including multi-fidelity solvers, metamodeling, active learning, dimensionality reduction, and robust multi-objective optimization techniques.

THE PARTNERS

- Consiglio Nazionale delle Ricerche – Istituto di Ingegneria del Mare
- Università Roma Tre
- Sapienza Università di Roma



BIODRONES
PRIN 2022



SAPIENZA
UNIVERSITÀ DI ROMA

<https://sites.google.com/inm.cnr.it/biodrones>

<https://www.linkedin.com/company/biodrones>

